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Abstract

A method for controlling a damper of a vehicle is provided, wherein the vehicle includes a front damper and a rear damper and a damping force of the dampers is controlled by respective data detected by a steering angle sensor, a vehicle speed sensor and a yaw rate sensor. First, steering angle data, vehicle speed data and yaw rate data are inputted in step (a) and a desired yaw rate is calculated in step (b) by using the steering angle data, the vehicle speed data and a specification of the vehicle. Then, the desired yaw rate is compared in step (c) with the yaw rate data provided from the yaw rate sensor. Thereafter, it is determined in step (d) whether the vehicle is over-steered or under-steered depending on the comparison result obtained in the step (C). Finally, the damping force of the damper is controlled in step (e) in response to the determination result in the step (d).